Technical Datasheet



Designation: Part. N°.: Elektronischer Entlader, Typ smart-D 210

810547



Technical data

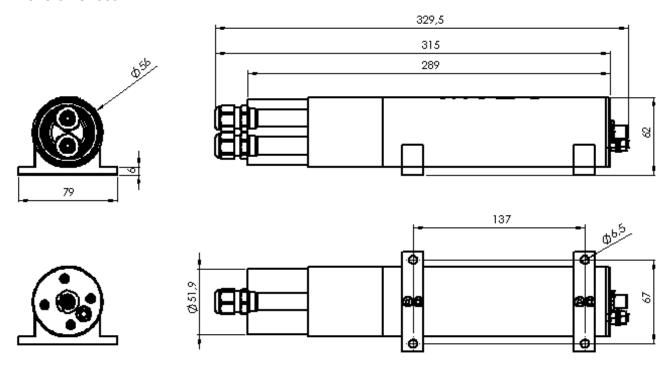
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Rated voltage	100 kV DC
Test voltage	120 kV DC
Max.operating current	1 mA (HV- Circuit)
High-voltage connection	4 mm socket
Number of hv-connections	2
Insertion depth	≥ 70 mm (grease filling required)
Diameter HV cable	6 - 9,5 mm
Ground connection	M6 bolt
Permissible leakage current	≤ 10 µA at 100 kV
Discharge time for 100kV/2nF	≤1s
Switching cycles	> 1 Mio.
Signal level and permissible current consumption according to PLC standard IEC61131	
Control voltage	24 V DC -15% / +20%
Drive current	≤ 500 mA
Reverse polarity protection	60 V
Signal level HIGH	11 – 30 V DC
Signal level LOW	-3 – 5 V DC
Discharge control signal	LOW / HIGH (aktive / inactive)
Fault feedback	HIGH / LOW (no fault / fault)
Connector type	M12 5-pin A-coded circular connector
Ambient conditions	+5° C to +70° C max. 90 % r.H.
Max. storage conditions	-10° C to +70° C
Dimensions	See dimension sheet
Weight	Approx. 1,5 kg
Control unit protection class	IP 54
ATEX	Kat. 3GD

Stand: 18.03.2024

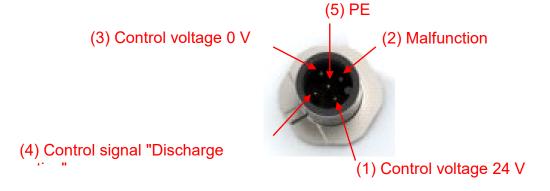
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Dimension sheet



Pin assignment



Description

The electronic discharger is used as part of the high-voltage-supply of electrostatic painting systems within the painting environment. Its main function is to discharge the energy stored in the system. The process should be as fast and trouble-free as possible.

The discharger is connected in parallel to the HV generator, so it has 2 HV connections, a) from the high-voltage generator and b) to the spray system. The two high-voltage connections are electrically connected to each other. In normal operation (not activated), only a small leakage current of max. 10µA flows via the electronic discharger. If the discharger is activated, a constant discharge current flows through it, which discharges a high-voltage system with 2 nF and 100 kV within one second.

The high-voltage part of the electronic discharger is completely encapsulated in epoxy resin, which means that it works in any position and can be used on a robot arm.

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